

**Amendments To The Claims:**

1. **(Currently Amended):** Gripping tool for automatic laboratory machines, with
  - gripping appliances (9, 10) for gripping vessels, the gripping appliances (9, 10) comprising needles (15, 16) and/or liners (21, 22), directed towards each other,
  - an appliance for converting and/or transferring (42, 45) of rotational movements, the ~~power-take-off~~ of which is coupled with the gripping appliances (9, 10) in order to drive the gripping appliances (9,10),
  - a coupling appliance (49) ~~for detachable connection~~ connectable with a rotational drive appliance ~~(78)~~ of a tool support (66) of an automatic laboratory machine, which is coupled with [[the]] a rotational drive of the appliance for converting and/or transferring (42, 45) in order to drive the gripping tool, and
  - a mounting appliance (35, 36) ~~for detachable mounting of by which~~ the gripping tool (1) is mountable on the tool support (66) of the automatic laboratory machine, while the coupling appliance (49) is connected with the rotational drive appliance (78) of the tool support (66).
2. **(Original):** Gripping tool according to claim 1, in which the gripping appliances are swingably mounted gripping levers (9, 10).
3. **(Original):** Gripping tool according to claim 2, in which the gripping levers (9, 10) have approximately parallel grapplers (11, 12) and offset driving arms (13, 14), directed towards each other, with the adjacent ends of which the drive of the appliance for converting and/or transferring (42, 45) is coupled.
4. **(Cancelled):**
5. **(Currently Amended):** Gripping tool according to claim [[4]] 1, in which gripping appliances (9, 10) comprise protective sleeves (17, 18) equipped with springs, disposed concentrically around the needles (15, 16), and/or liners (21, 22), disposed concentrically around the needles.

6. **(Original):** Gripping tool according to claim 1, which has a spring appliance (31) clamping the gripping appliances (9, 10) together.

7. **(Currently Amended):** Gripping tool according to claim 6, in which the spring appliance (31) presses the gripping appliances (9, 10) against [[the]] a power take-off of the appliance for converting and/or transferring (42, 45).

8. **(Original):** Gripping tool according to claim 1, in which the appliance for converting and/or transferring (42, 45) has an axially movable, threaded nut (42) secured against rotation, acting on the gripping appliances (9, 10) with a front side, and a spindle (45), screwable in the threaded nut (42) and connected with the coupling appliance (49) in a manner secured against rotation.

9. **(Original):** Gripping tool according to claim 1, which comprises an appliance for indicating (50) the position of the gripping appliances (9, 10), which is feelable by a sensor (84) of the tool support (66) while the gripping tool (1) is mounted on the tool support (66).

10. **(Previously Presented):** Gripping tool according to claim 9, in which the appliance for indicating is a pin (50) fixedly connected with a threaded nut.

11. **(Original):** Gripping tool according to claim 1, in which the coupling appliance is a driving feature (49), connected with the drive of the appliance for converting and/or transferring (42, 45) in a manner secured against rotation, with at least one working surface for a rotational drive appliance.

12. **(Previously Presented):** Gripping tool according to claim 1, in which the mounting appliance has a hollow mounting spigot (35) and the coupling appliance (49) is disposed in the mounting spigot or sticks out of it, and/or an appliance for indicating (50) is disposed in the mounting spigot (35) or sticks out of it.

13. **(Original):** Gripping tool according to claim 12, in which the mounting spigot (35) on the outside has a connection part (36) of a detachable, positively fitting connection.

14. **(Original):** Gripping tool according to claim 13, in which the mounting spigot has a bayonet-type connection part (36).

15. **(Original):** Gripping tool according to claim 12, in which the mounting spigot (35) has at least one cylinder part (35', 35'') and at least one conical base part (35''').

16. **(Original):** Gripping tool according to claim 1, on which a chip is disposed with data of the gripping tool (1), readable from the outside.

17. **(Withdrawn):** Dosage tool for automatic laboratory machines, with

- at least one piston-cylinder appliance (59, 60),
- an appliance for converting and/or transferring (42, 45) of movements, the power take-off of which is coupled with the piston-cylinder appliance (59, 60) in order to drive it,
- a coupling appliance (49) for detachable connection with a drive appliance (78) of a tool support (66) of an automatic laboratory machine, which is coupled with the drive of the appliance for converting and/or transferring (42, 45) in order to drive it,
- a mounting appliance (35, 36) for detachable mounting of the dosage tool (52) on the tool support (66) of the automatic laboratory machine, when the coupling appliance (49) is connected with the drive appliance (78) of the tool support (66).
- an appliance for indicating (50) the position of the piston (59) of the piston-cylinder appliance (59, 60), which is feelable by a sensor (84) of the tool support (66) while the dosage tool (52) is mounted on the tool support (66).

18. **(Withdrawn):** Dosage tool according to claim 17, in which the appliance for converting and/or transferring (42, 45) has an axially movable, threaded nut (42) secured against rotation, acting on the piston of the piston-cylinder appliance with a front side, and a spindle (45),

screwable in the threaded nut (42) and connected with the coupling appliance in a manner secured against rotation.

19. **(Withdrawn):** Dosage tool according to claim 18, in which the appliance for indicating (50) is a pin, fixedly connected with the threaded nut (42).

20. **(Withdrawn):** Dosage tool according to claim 17, in which the coupling appliance is a driving feature (49), connected with the drive of the appliance for converting and/or transferring (42, 45) in a manner secured against rotation, with at least one working surface for a rotational drive appliance of the tool support (66).

21. **(Withdrawn):** Dosage tool according to claim 17, in which the mounting appliance (35, 36) has a hollow mounting spigot (35) and the coupling appliance (49) is disposed in the mounting spigot (35) or sticks out of it, and/or the appliance for indicating (50) is disposed in the mounting spigot (35) or sticks out of it.

22. **(Withdrawn):** Dosage tool according to claim 21, in which the mounting spigot (35) on the outside has a connection part (36) of a detachable, positively fitting connection.

23. **(Withdrawn):** Dosage tool according to claim 22, in which the mounting spigot (35) has a bayonet-type locking part (36).

24. **(Withdrawn):** Dosage tool according to claim 21, in which the mounting spigot (35) has at least one cylinder part (35', 35'') and at least one conical base part (35'').

25. **(Withdrawn):** Dosage tool according to claim 17, on which a chip is disposed with data of the dosage tool (52), readable from the outside.

26. **(Withdrawn):** Tool support for an automatic laboratory machine, particularly suited for supporting and moving of gripping tools (1) and dosage tools (52) according to claim 1, with

- a drive appliance (78) for driving of a gripping tool or of a dosage tool (1, 52) at option,
- a further coupling appliance (79) for connecting the drive appliance (78) with a coupling appliance (49) of a gripping tool or of a dosage tool (1, 52) at option,
- a further mounting appliance (70, 71) for mounting the mounting appliance (35, 36) of a gripping tool or of a dosage tool (1, 52) at option, while the coupling appliances (49, 79) of the tool support (66) and the gripping tool (1) or the dosage tool (52) are coupled with each other, and
- a control appliance for controlling the movements of a gripping tool (1) or of a dosage tool (52) at option.

27. **(Withdrawn):** Tool support according to claim 26 with a rotational drive appliance (80).

28. **(Withdrawn):** Tool support according to claim 27, in which the further coupling appliance (79) has at least one further working surface for the transmission of a rotational drive movement.

29. **(Withdrawn):** Tool support according to claim 26, in which the mounting appliance has an accommodation (70) for a mounting spigot (35) of a gripping- or dosage tool (1, 52), and the further coupling appliance (79) is associated to the accommodation (70), in order to couple in the coupling appliance (49) of the gripping- or dosage tool (1, 52) while the mounting spigot (35) is disposed in the accommodation (70).

30. **(Withdrawn):** Tool support according to claim 29, in which a further bayonet-type connection part (71) for detachable connection with a bayonet-type connection part (35, 36) of the mounting spigot (35) of a gripping- or dosage equipment (1, 52) is associated to the further accommodation (70).

31. **(Withdrawn):** Tool support according to claim 30, in which the further bayonet-type connection part (71) can be driven by a motor, and the control appliance controls the movements of the further bayonet-type connection part (71).

32. **(Withdrawn)**: Tool support according to claims 26, in which a sensor (84) is associated to the accommodation (70) in order to feel an appliance for indicating (50) of a gripping- or dosage tool (1, 52), disposed in the accommodation (70) with the mounting spigot (35), and the sensor is connected with the control appliance, in order to control the movements, depending on the position of the gripping appliances (9, 10) or the piston (60).

33. **(Withdrawn)**: Tool support according to claim 26, which has a further sensor (86) for feeling data of a gripping- or dosage tool (1, 52), which is connected with the control element in order to control the movements, depending of the data of the gripping tool (1) or the dosage tool (52) employed, respectively.

34. **(Withdrawn)**: Tool support according to claim 26, with a displacement appliance facility for displacing the tool support along at least one and/or for at least one spatial axis, which displacement is controllable by the control appliance, in order to reach different vessel positions with the gripping tool (1), and different dosage positions with the dosage tool (52).

35. **(Withdrawn and Previously Presented)**: System for gripping and moving of vessels and/or dosage of samples with a gripping tool (1) according to claim 1, and a tool support (66) with

- a drive appliance (78) for driving of a gripping tool or of a dosage tool (1, 52) at option,
- a further coupling appliance (79) for connecting the drive appliance (78) with a coupling appliance (49) of a gripping tool or of a dosage tool (1, 52) at option,
- a further mounting appliance (70, 71) for mounting the mounting appliance (35, 36) of a gripping tool or of a dosage tool (1, 52) at option, while the coupling appliances (49, 79) of the tool support (66) and the gripping tool (1) or the dosage tool (52) are coupled with each other, and
- a control appliance for controlling the movements of a gripping tool (1) or of a dosage tool (52) at option.

36. **(Previously Presented and Withdrawn)** A gripping tool for automatic laboratory machines, the gripping tool comprising:

a bottom part, the bottom part comprising:

a bearing box, the bearing box defining a passage;

a first gripping lever, the first gripping lever engaged to the bearing box, the first gripping lever comprising a first grappler and a first drive arm;

a first T-shaped grappler extension, the first T-shaped grappler extension engaged to the first grappler;

a second gripping lever, the second gripping lever engaged to the bearing box, the second gripping lever comprising a second grappler and a second drive arm;

a second T-shaped grappler extension, the second T-shaped grappler extension engaged to the second grappler;

an upper part, the upper part comprising:

a mounting spigot, the mounting spigot comprising a base part, a first claw, and a second claw, the first and second claws forming a bayonet-type connection;

a mounting plate, the mounting plate fixedly connected to the base part of the mounting spigot;

a bore, the bore extending longitudinally through the mounting spigot and transversally through the mounting plate, the bore being aligned with the passage of the bearing box;

a threaded nut, the threaded nut being disposed within the bore, the threaded nut having a cylindrical pin engaged to a wing of the threaded nut;

a spindle, the spindle being screwed into the threaded nut;

a driving feature, the driving feature engaged to a portion of the spindle;

wherein the bearing box of the bottom part is engaged to the mounting plate of the upper part and the gripping tool is detachably mounted to a tool support by the bayonet-type connection.

37. **(Currently Amended)** Gripping tool for automatic laboratory machines, the gripping tool comprising needles (15, 16) and/or liners (21, 22), directed towards each other;

gripping appliances (9, 10) for gripping vessels, the gripping appliances comprising;

an appliance for converting and/or transferring (42, 45) of rotational movements, the

power-take-off of which is coupled with the gripping appliances (9, 10) in order to drive the gripping appliances (9,10);

a coupling appliance (49) ~~for detachable connection~~ connectable with a rotational drive appliance ~~(78)~~ of a tool support (66) of an automatic laboratory machine, which is coupled with the drive of the appliance for converting and/or transferring (42, 45) in order to drive the gripping tool, and

a mounting appliance (35, 36) ~~for detachable mounting of by which~~ the gripping tool (1) is mountable on the tool support (66) of the automatic laboratory machine, while the coupling appliance (49) is connected with ~~the rotational drive appliance (78) of~~ the tool support (66).<sub>[[;]]</sub>

38. **(Previously Presented)** Gripping tool according to claim 37, the gripping appliances (9, 10) further comprising protective sleeves (17, 18) equipped with springs disposed concentrically around the needles (15, 16), and/or liners (21, 22) disposed concentrically around the needles.